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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

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sampled data must be converted into digital data.

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Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata. Prentice-Hall, 1995. † Computer Controlled Systems, by "Astr~om and Wittenmark. Prentice-Hall,

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1997.

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Such a discrete-time control system consists of four major parts:
1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC).
 $3 + - r(t) e(t) \text{ ADC } \mu\text{P} \text{ DAC } u(t) \text{ Plant } ? ? y(t) 4$

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and optimal control).

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Discrete time control systems are control systems in which one or more variables can change only at discrete instants of time.

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These instants, which may be denoted by kT ($k=0,1,2,\dots$) specify the times at which some physical measurement is performed or the times at which the memory of a digital computer is read out.

ADVANCE CONTROL SYSTEM ENGINEERING

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2. Open-loop Control Systems Those systems in which the output has no effect on the control action are called open-loop control systems. In other words, in an open-loop control system, the output is neither measured nor fed back for comparison with the

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input. (1) To control the plant directly without using feedback
Feedforward control. 36 Example.

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